Numerical simulation of crossing-shock-wave/turbulent-boundary-layer interaction using a two-equation model of turbulence

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A crossing-shock-wave/turbulent-boundary-layer interaction is investigated using the $k-\epsilon$ turbulence model with a new low-Reynolds-number model based on the approach of Saffman (1970) and Speziale *et al.* (1990). The crossing shocks are generated by two wedge-shaped fins with wedge angles α_1 and α_2 attached normal to a flat plate on which an equilibrium supersonic turbulent boundary layer has developed. Two configurations, corresponding to the experiments of Zheltovodov *et al.* (1994, 1998*a, b*), are considered. The free-stream Mach number is 3.9, and the fin angles are $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$ and $(7^{\circ}, 11^{\circ})$. The computed surface pressure displays very good agreement with experiment. The computed surface skin friction lines are in close agreement with experiment for the initial separation, and are in qualitative agreement within the crossing shock interaction region. The computed heat transfer is in good agreement with experiment for the $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$ configuration. For the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ configuration, the heat transfer is significantly overpredicted within the three-dimensional interaction. The adiabatic wall temperature is accurately predicted for both configurations.

1. Introduction

Three-dimensional shock-wave/turbulent-boundary-layer interactions commonly occur in a wide range of applications in high-speed flows and strongly influence the flow-field characteristics (Greene 1970; Settles & Dolling 1986, 1990; Zheltovodov 1996). For sufficiently strong shocks, the flow pattern includes separation of the boundary layer and formation of vortices. An adequate understanding of the flow structures caused by shock-wave/turbulent-boundary-layer interaction, and the ability of a theoretical model to accurately predict the aerothermodynamic loads (i.e. surface pressure, skin friction and heat transfer), are crucial for the improved design of supersonic aircraft components such as inlets or nozzles.

Recent research efforts have concentrated on a particular family of flows involving three-dimensional shock-wave/turbulent-boundary-layer interactions, namely the crossing shock ('double fin') interactions (figure 1), due to applications to high-speed inlets (Edwards 1976; Sakell, Knight & Zheltovodov 1994). Significant research efforts

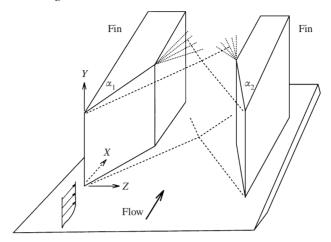


FIGURE 1. Crossing shock ('double fin').

have been concentrated on the development and evaluation of turbulence models capable of providing accurate predictions of the flow structure and aerothermodynamic loads on the bottom flat-plate surface (Narayanswami et al. 1992; Narayanswami, Horstman & Knight 1993a; Narayanswami, Knight & Horstman 1993c); Garrison et al. 1992; Garrison & Settles 1992, 1993; Garrison 1994; Garrison et al. 1994; Gaitonde, Shang & Visbal 1995; Gaitonde & Shang 1995; Knight et al. 1995a; Gaitonde et al. 1997, 1998). A review of theoretical and experimental studies of the crossing-shock interactions can be found in Knight et al. (1995b), Degrez (1993), Zheltovodov, Maksimov & Shevchenko (1998a) and Zheltovodov et al. (1998b). The computed flows generally exhibit good agreement with experimental data for surface pressure, shock structure, and boundary layer profiles of pitot pressure and yaw angle. However, the accurate prediction of the surface heat transfer and skin friction remains a challenging problem (Narayanswami et al. 1993a; Garrison et al. 1994).

While the surface pressure is to a large extent determined by the inviscid rotational character of the flow and therefore not strongly affected by the particular choice of the theoretical turbulence model (Knight et al. 1995b), the surface derivative quantities (i.e. skin friction and heat transfer) are strongly influenced by the turbulence model. Consequently, one of the greatest challenges for accurately computing the crossing shock interaction is the modelling of the turbulence quantities of such flows. The two-equation $k-\epsilon$ model is a popular choice since it can in principle predict complex flow fields better than algebraic models and is significantly simpler than sophisticated higher-order closures. A major difficulty in the implementation of the $k-\epsilon$ model is the treatment of the near-wall region, where the classical high Reynolds number $k-\epsilon$ model is invalid. To overcome this difficulty and allow integration to the boundary, wall damping functions can be introduced which lead to the creation of a so-called 'low-Reynolds-number $k-\epsilon$ model'. Many such models have been developed in recent years and significant research efforts have been invested in the validation of different turbulence models for the computation of flows with shock-wave/boundary-layer interaction, in particular flows with crossing shock interactions. In this paper, we present results using the $k-\epsilon$ model with the new low Reynolds number model of Becht & Knight (1995) which was developed on the basis of three principles, namely (i) the model employs the physical dissipation rate ϵ , (ii) the normal distance n is avoided, and (iii) the minimum number of modifications is introduced, as described

by Speziale, Abid & Anderson (1990). The low Reynolds number modifications, based on the ideas of Saffman (1970) and Speziale *et al.* (1990), are (i) incorporation of molecular diffusion of k and ϵ , (ii) modification of the turbulent eddy viscosity μ_T to provide proper asymptotic behaviour near the wall, and (iii) modification of the dissipation of ϵ to avoid singularities in the ϵ equation near the wall.

The objective of the present paper is to assess the capability of the standard $k-\epsilon$ model with the new low Reynolds number model to predict crossing-shock-wave/turbulent-boundary-layer interactions. The experimental configuration of Zheltovodov *et al.* (1994) is considered. Complete details of the experiment are provided in Zheltovodov *et al.* (1998a, b). Computational results are compared to the experimental data at $M_{\infty} = 3.9$ for $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$ and $(7^{\circ}, 11^{\circ})$. Comparison is also presented with previous computational results of Knight *et al.* (1995b) using the $k-\epsilon$ Chien model, and Zha & Knight (1996) using a full Reynolds stress equation model for the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ case.

2. Governing equations

2.1. Reynolds-averaged Navier-Stokes

The Reynolds-averaged equations for conservation of mass, momentum and energy are

$$\frac{\partial \bar{\rho}}{\partial t} + \frac{\partial \bar{\rho} \tilde{u}_i}{\partial x_i} = 0, \tag{2.1}$$

$$\frac{\partial \bar{\rho}\tilde{u}_i}{\partial t} + \frac{\partial \bar{\rho}\tilde{u}_i\tilde{u}_j}{\partial x_j} = -\frac{\partial \bar{p}}{\partial x_i} + \frac{\partial \mathcal{T}_{ij}}{\partial x_j},\tag{2.2}$$

$$\frac{\partial \bar{\rho}\tilde{e}}{\partial t} + \frac{\partial \left(\bar{\rho}\tilde{e} + \bar{p}\right)\tilde{u}_i}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\mathcal{Q}_i + \mathcal{T}_{ij}\tilde{u}_j \right), \tag{2.3}$$

where the Einstein summation convention is employed and the overbar represents ensemble averaging, i.e.

$$\bar{f} = \lim_{n \to \infty} \frac{1}{n} \sum_{\nu=1}^{\nu=n} f^{(\nu)}$$
 (2.4)

where $f^{(v)}$ are the individual realizations of the variable f(x, y, z, t). A mass-averaged (Favre-averaged) variable \tilde{f} is defined as the density-weighted ensemble average,

$$\tilde{f} = \frac{1}{\bar{\rho}} \lim_{n \to \infty} \frac{1}{n} \sum_{\nu=1}^{\nu=n} (\rho f)^{(\nu)}$$
(2.5)

and the fluctuating variable f'' in the mass-averaged expansion is

$$f^{"} = f - \tilde{f}. \tag{2.6}$$

Alternatively, the fluctuating variable f' in the unweighted expansion is

$$f' = f - \bar{f}. \tag{2.7}$$

In (2.1) to (2.3), $\bar{\rho}$ is the mean density, \tilde{u}_i is the mass-averaged velocity, \bar{p} is the mean pressure, and \tilde{e} is the mass-averaged total energy per unit mass,

$$\tilde{e} = c_v \tilde{T} + \frac{1}{2} \tilde{u}_i \tilde{u}_i + \tilde{k} \tag{2.8}$$

where \tilde{k} is the mass-averaged turbulence kinetic energy

$$\bar{\rho}\tilde{k} = \frac{1}{2}\overline{\rho u_i'' u_i''}.\tag{2.9}$$

The total stress is defined as

$$\mathscr{T}_{ij} = -\overline{\rho u_i^{"} u_j^{"}} + \overline{\tau}_{ij} \tag{2.10}$$

where the mean molecular viscous stress $\bar{\tau}_{ii}$ is

$$\bar{\tau}_{ij} = -\frac{2}{3}\tilde{\mu}\frac{\partial \tilde{u}_k}{\partial x_k}\delta_{ij} + \tilde{\mu}\left(\frac{\partial \tilde{u}_j}{\partial x_i} + \frac{\partial \tilde{u}_i}{\partial x_j}\right)$$
(2.11)

where $\tilde{\mu} \equiv \mu(\tilde{T})$. The total heat flux is

$$\mathcal{Q}_i = -c_p \overline{\rho T'' u_i''} - \overline{q}_i \tag{2.12}$$

where the molecular heat flux is

$$\bar{q}_i = -\frac{c_p \tilde{\mu}}{Pr} \frac{\partial \tilde{T}}{\partial x_i} \tag{2.13}$$

and Pr is the molecular Prandtl number.

The Reynolds-averaged equations (2.1) to (2.3) neglect the triple correlation $\frac{1}{2} \rho u_j^{"} u_i^{"} u_i^{"}$ and velocity-molecular shear correlation $\overline{u_i^{"} \tau_{ij}}$ which are negligible under practical circumstances (Knight 1993b).

2.2. Turbulence model for high Reynolds number

The closure of the Reynolds-averaged equations (2.1) to (2.3) requires specification of the turbulent stress $-\overline{\rho u_i^n u_j^n}$ and turbulent heat flux $-c_p \rho T^n u_i^n$. We adopt the high Reynolds number form of the two-equation $k-\epsilon$ model of Jones & Launder (1972). The equation for the turbulence kinetic energy \tilde{k} is taken to be

$$\frac{\partial \bar{\rho}\tilde{k}}{\partial t} + \frac{\partial \bar{\rho}\tilde{k}\tilde{u}_{i}}{\partial x_{i}} = -\overline{\rho u_{i}''u_{j}''} \frac{\partial \tilde{u}_{i}}{\partial x_{j}} - \bar{\rho}\tilde{\epsilon} + \frac{\partial}{\partial x_{i}} \left(\frac{\mu_{T}}{\bar{\rho}\sigma_{k}} \frac{\partial \bar{\rho}\tilde{k}}{\partial x_{i}} \right). \tag{2.14}$$

The equation for the dissipation is

$$\frac{\partial \bar{\rho}\tilde{\epsilon}}{\partial t} + \frac{\partial \bar{\rho}\tilde{u}_{i}\tilde{\epsilon}}{\partial x_{i}} = -C_{\epsilon 1}\frac{\tilde{\epsilon}}{\tilde{k}}\frac{\partial u_{i}''u_{j}''}{\partial x_{i}}\frac{\partial \tilde{u}_{i}}{\partial x_{j}} - C_{\epsilon 2}\bar{\rho}\frac{\tilde{\epsilon}^{2}}{\tilde{k}} + \frac{\partial}{\partial x_{i}}\left(\frac{\mu_{T}}{\sigma_{\epsilon}}\frac{\partial \tilde{\epsilon}}{\partial x_{i}}\right). \tag{2.15}$$

The turbulent stresses are

$$-\overline{\rho u_i'' u_j''} = \mu_T \left(\frac{\partial \tilde{u}_i}{\partial x_i} + \frac{\partial \tilde{u}_j}{\partial x_i} - \frac{2}{3} \frac{\partial \tilde{u}_k}{\partial x_k} \delta_{ij} \right) - \frac{2}{3} \bar{\rho} \tilde{k} \delta_{ij}$$
 (2.16)

and the turbulent heat flux is

$$-c_{p}\overline{\rho T''u_{i}''} = c_{p}\frac{\mu_{T}}{Pr_{t}}\frac{\partial \tilde{T}}{\partial x_{i}}$$
(2.17)

where the turbulent eddy viscosity is

$$\mu_T = \bar{\rho} C_\mu \frac{\tilde{k}^2}{\tilde{\epsilon}}.\tag{2.18}$$

The turbulence model constants are based on the standard values (Launder & Sharma 1974; Wilcox 1993) and are presented in table 1. The governing equations (2.14) to (2.18) are applicable only within fully turbulent regions, and consequently

Constant	Value
C_{μ}	0.09
$\overset{\circ}{C_{\epsilon_1}}$	1.44
$C_{\epsilon_2}^{-1}$	1.92
Pr_t	0.9
σ_k	1.0
σ_{ϵ}	1.3

Table 1. Standard $k-\epsilon$ model constants.

cannot be integrated directly to a solid boundary. The low Reynolds number modifications to allow integration to a solid boundary are presented in the following section.

2.3. Turbulence model for low Reynolds number

We present the motivation, definition and calibration of the low Reynolds number model.

2.3.1. Motivation

The first low Reynolds number modification to the $k-\epsilon$ model was developed by Jones & Launder (1972, 1973). The modifications included the formal introduction of molecular diffusion in the k and ϵ equations, incorporation of a functional dependence of two of the model constants on the turbulence Reynolds number $R_t \equiv \rho k^2/\epsilon \mu$, introduction of a pseudo-dissipation rate $\epsilon' = \epsilon - \epsilon_w$ (where ϵ_w is the turbulent dissipation rate at the wall) apparently on the basis of numerical considerations, and inclusion of additional source terms in the k and ϵ equations.

Numerous other low Reynolds number modifications for the k- ϵ model have been proposed including, for example, Launder & Sharma (1974), Hoffman (1975), Reynolds (1976), Hassid & Poreh (1978), Dutoya & Michard (1981), Lam & Bremhorst (1981), Chien (1982), Myong & Kasagi (1990), So, Zhang & Speziale (1991), Yang & Shih (1993), and Fan, Lakshminarayana & Barnett (1993). A detailed examination of the first seven of these was performed by Patel, Rodi & Scheuerer (1985) who concluded that the models of Launder & Sharma, Chien, and Lam & Bremhorst yielded comparable results and are significantly more accurate than the others.

The low Reynolds number k– ϵ models recommended by Patel *et al.*, as well as many subsequent models (e.g. Myong & Kasagi 1990; So *et al.* 1991; Fan *et al.* 1993), are characterized by one or more of the following limitations:

- (a) Pseudo-dissipation rate The pseudo-dissipation rate, introduced by Jones & Launder (1972) for numerical reasons, is unphysical. Its use has been criticized for many years (e.g. Reynolds 1976). Although it might be argued that the use of the pseudo-dissipation rate is fundamentally a philosophical question, nevertheless we maintain that, in the absence of a compelling numerical requirement, it is unnecessary. As described later, we have found no numerical difficulties in using the dissipation rate ϵ and imposing the physically correct boundary condition for ϵ at the wall.
- (b) Dependence on n The normal distance n, employed in many low Reynolds number modifications in the form of the dimensionless distance $n^+ \equiv nu_*/v_w$ (where $u_* \equiv \sqrt{\tau_w/\rho_w}$ and τ_w is the (local) wall shear stress) or $R_n \equiv \sqrt{k}n/v$, cannot be uniquely defined in all cases. This occurs even for simple geometries (e.g. in the vicinity of a

two-dimensional compression corner, in the neighbourhood of a three-dimensional corner, etc.).

(c) Extensive number of modifications Speziale et al. (1990) demonstrated that a minimum of three functional modifications to the $k-\epsilon$ model is required for integration to a solid boundary, namely (i) incorporation of molecular diffusion of k and ϵ (similar to the suggestion of Saffman 1970), (ii) modification of the turbulent eddy viscosity μ_T to provide proper asymptotic behaviour near the wall, and (iii) modification of the dissipation of ϵ to avoid singularities in the ϵ equation near the wall. Many low Reynolds number modifications employ significantly more than this minimum number. While the choice of the low Reynolds number modifications is not unique and the ultimate value is determined by the ability of the model to predict turbulent flows, nonetheless we consider simplicity of the low Reynolds number modifications to be an important attribute.

The new low Reynolds number model avoids all of these limitations.

2.3.2. Equations for \tilde{k} and $\tilde{\epsilon}$

The equation for the turbulence kinetic energy (2.14) is modified in two ways. First, molecular diffusion of \tilde{k} is formally incorporated in the manner proposed by Saffman (1970):

$$\frac{\partial \bar{\rho}\tilde{k}}{\partial t} + \frac{\partial \bar{\rho}\tilde{k}\tilde{u}_{i}}{\partial x_{i}} = -\overline{\rho u_{i}''u_{j}''} \frac{\partial \tilde{u}_{i}}{\partial x_{j}} - \bar{\rho}\tilde{\epsilon} + \frac{\partial}{\partial x_{i}} \left(\frac{\mu_{T}}{\bar{\rho}\sigma_{k}} \frac{\partial \bar{\rho}\tilde{k}}{\partial x_{i}} + \tilde{\mu} \frac{\partial \tilde{k}}{\partial x_{i}} \right). \tag{2.19}$$

Second, the turbulent eddy viscosity is modified by a dimensionless factor f_{μ} to provide the correct asymptotic behaviour of the turbulent stresses close to a solid boundary

$$\mu_T = \bar{\rho} C_\mu f_\mu \frac{\tilde{k}^2}{\tilde{\epsilon}} \tag{2.20}$$

where asymptotic analysis (see, for example, Speziale *et al.* 1990) shows† $f_{\mu} = O(n^{-1})$ as $n \to 0$. Additionally, $f_{\mu} \to 1$ as $n \to \infty$. The dimensionless function f_{μ} is determined through consideration of the viscous sublayer and logarithmic region of an incompressible flat-plate turbulent boundary layer as described in the next section.

The equation for the dissipation is likewise modified by incorporation of molecular diffusion of $\tilde{\epsilon}$ in the manner proposed by Saffman (1970) and the inclusion of the dimensionless function f_2 for the dissipation term

$$\frac{\partial \bar{\rho}\tilde{\epsilon}}{\partial t} + \frac{\partial \bar{\rho}\tilde{u}_{i}\tilde{\epsilon}}{\partial x_{i}} = -C_{\epsilon 1}\frac{\tilde{\epsilon}}{\tilde{k}}\frac{\partial \bar{u}''_{i}u''_{j}}{\partial x_{i}}\frac{\partial \tilde{u}_{i}}{\partial x_{i}} - C_{\epsilon 2}f_{2}\bar{\rho}\frac{\tilde{\epsilon}^{2}}{\tilde{k}} + \frac{\partial}{\partial x_{i}}\left[\left(\frac{\mu_{T}}{\sigma_{\epsilon}} + \tilde{\mu}\right)\frac{\partial \tilde{\epsilon}}{\partial x_{i}}\right]$$
(2.21)

where asymptotic analysis (Speziale *et al.* 1990) indicates $f_2 = O(n^2)$ as $n \to 0$, and $f_2 \to 1$ as $n \to \infty$.

The dimensionless function f_2 is taken to be

$$f_2 = 1 - \exp\left(-C_{\epsilon_s}\sqrt{R_t}\right) \tag{2.22}$$

where R_t is the turbulence Reynolds number

$$R_t = \frac{\bar{\rho}\tilde{k}^2}{\tilde{\mu}\tilde{\epsilon}}.\tag{2.23}$$

This provides the proper asymptotic behaviour near the wall assuming $\epsilon \to \epsilon_w$ as

† The argument requires the assumption that the density fluctuations at the wall may be neglected. This is certainly true for incompressible flow. Although not formally correct for compressible flows (adiabatic or isothermal walls), it is nonetheless invoked (e.g. Zhang et al. 1992).

 $n \to 0$ where ϵ_w is the (positive) value of the turbulence kinetic energy dissipation at the wall, and $\tilde{k} = O(n^2)$ as $n \to 0$. The dimensionless constant C_{ϵ_s} is determined by comparison with direct numerical simulation (DNS) results as described below.

The boundary conditions for the turbulence variables at a solid boundary are

$$\tilde{k} = 0, \quad \tilde{\epsilon} = \frac{2\tilde{\mu}_w}{\bar{\rho}_w} \left(\frac{\partial\sqrt{k}}{\partial n}\right)^2,$$
(2.24)

where n is the normal distance to the boundary and the subscript w implies evaluation at the wall. These boundary conditions are exact.

2.3.3. Determination of f_{μ} and C_{ϵ_s}

The low Reynolds number model introduces the dimensionless functions f_{μ} and f_2 . The functional form of f_{μ} and the constant C_{ϵ_s} in f_2 are determined through consideration of the viscous sublayer and logarithmic region of an incompressible flat-plate turbulent boundary layer (i.e. the 'constant stress layer') in the manner proposed by Saffman (1970). In this region, convective effects are negligible and the model equations are

$$0 = \frac{\partial}{\partial y} \left(-\overline{\rho u''v''} + \mu \frac{\partial u}{\partial y} \right), \tag{2.25}$$

$$0 = -\overline{\rho u''v''} \frac{\partial u}{\partial y} - \rho \epsilon + \frac{\partial}{\partial y} \left[\left(\frac{\mu_T}{\sigma_k} + \mu \right) \frac{\partial k}{\partial y} \right], \tag{2.26}$$

$$0 = -C_{\epsilon_1} \frac{\epsilon}{k} \overline{\rho u'' v''} \frac{\partial u}{\partial y} - C_{\epsilon_2} f_2 \frac{\rho \epsilon^2}{k} + \frac{\partial}{\partial y} \left[\left(\frac{\mu_T}{\sigma_{\epsilon}} + \mu \right) \frac{\partial \epsilon}{\partial y} \right], \tag{2.27}$$

where the Reynolds shear stress is

$$-\overline{\rho u''v''} = \mu_T \frac{\partial u}{\partial y} \tag{2.28}$$

and

$$\mu_T = \rho C_\mu f_\mu \frac{k^2}{\epsilon}.\tag{2.29}$$

The tilde is omitted since the flow is incompressible.

The boundary conditions at the wall are

$$u = 0, (2.30)$$

$$k = 0, (2.31)$$

$$\epsilon = \frac{2\mu}{\rho} \left(\frac{\partial \sqrt{k}}{\partial y} \right)^2, \tag{2.32}$$

and the asymptotic boundary conditions for $y \to \infty$ are

$$u = \frac{u_*}{\kappa} \ln\left(\frac{yu_*}{v}\right) + Bu_*,\tag{2.33}$$

$$k = \frac{u_*^2}{\sqrt{C_u}},\tag{2.34}$$

$$\epsilon = \frac{u_*^3}{\kappa v},\tag{2.35}$$

where $u_* = \sqrt{\tau_w/\rho}$ is the local friction velocity.

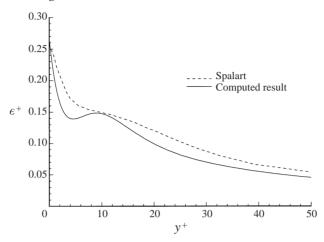


FIGURE 2. Predicted and DNS results for ϵ .

For the incompressible constant-stress layer, the following form of the turbulent eddy viscosity is assumed:

$$\mu_T = \begin{cases} \rho \kappa u_* y_m [2(y/y_m)^3 - (y/y_m)^5] & \text{for } y \leq y_m \\ \rho \kappa u_* y & \text{for } y > y_m. \end{cases}$$
 (2.36)

The functional form for μ_T satisfies the appropriate asymptotic forms (Wilcox 1993; Speziale *et al.* 1990) as $y \to 0$ and $y \to \infty$, and is continuously differentiable for all y. It is emphasized that equation (2.36) is employed only for the incompressible constant-stress-layer analysis.

The momentum equation (2.25) may be directly integrated, using (2.28) and (2.36) and subject to boundary conditions (2.30) and (2.33). The constant B in (2.33) depends on the value of y_m . It may be verified that $y_m = 33.0v/u_*$ yields B = 5.0 in agreement with experiment (Monin & Yaglom 1971).

The turbulence model equations (2.26) and (2.27) may be solved for k and ϵ subject to boundary conditions (2.31), (2.32), (2.34) and (2.35). The constant C_{ϵ_s} is determined by requiring $\epsilon_w = 0.26u_*^4/v$ in agreement with the DNS of Spalart (1988) for a flatplate turbulent boundary layer. This yields $C_{\epsilon_s} = 0.17$. Comparison of the predicted and DNS profiles for ϵ are presented in figure 2 where $\epsilon^+ = \epsilon v/u_*^4$.

The dimensionless function f_{μ} is then obtained from (2.29) as a function of R_t . The functions f_2 and f_{μ} are shown in figure 3. These functions are employed without modification for the subsequent computations. The low Reynolds number modifications are summarized in table 2.

2.3.4. Validation of the low Reynolds number model

A detailed validation of the low Reynolds number model was performed for adiabatic and isothermal flat-plate zero-pressure-gradient turbulent boundary layers from incompressible to Mach 6 in Becht & Knight (1995). We present results for incompressible flow since the improvements to the model are based on arguments for incompressible turbulent flow. We also present results for Mach 4 which corresponds to the free-stream conditions for the experiments of Zheltovodov *et al.* (1994, 1998*a, b*) for the crossing shock, and are representative of the accuracy of the model for Mach 2 to 6 (Becht & Knight 1995).

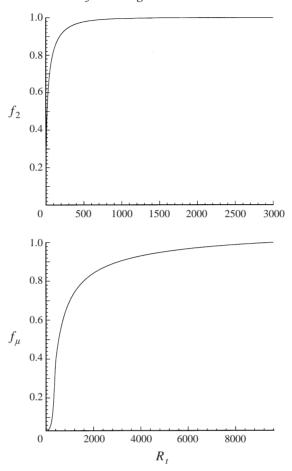


FIGURE 3. Functions f_2 and f_{μ} .

Function	Expression
$f_2(Re_t)$	$1 - \exp\left(-C_{\epsilon_s}\sqrt{R_t}\right)$ where $C_{\epsilon_s} = 0.17$
$f_{\mu}(Re_t)$	See figure 3
TABLE 2. Low R	eynolds number functions.

Incompressible flow

The predictions of the model equations for the incompressible flat-plate boundary layer experiment of Weighardt & Tillman (1951) are presented in figures 4 and 5. The computed and experimental skin friction agree to within 9%. The velocity profiles are displayed at $Re_{\theta} = 1.2 \times 10^4$ and agree within 2%.

Mach 4 adiabatic wall

The computed skin friction for the adiabatic Mach 4 turbulent boundary layer is compared with the empirical Van Driest II formula (Hopkins & Inouye 1971) in

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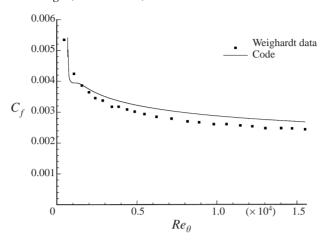


FIGURE 4. Skin friction coefficient from Weighardt & Tillman.

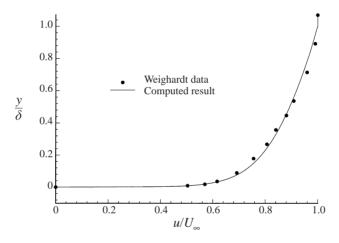


FIGURE 5. Velocity profile from Weighardt & Tillman.

figure 6. The predictions are within the experimental uncertainty $(\pm 10\%)$ for the entire range of Mach numbers (Becht & Knight 1995).

The computed velocity profile in the near-wall region is presented in figure 7 and compared with the compressible law of the wall (White 1974)

$$u_c = \frac{u_*}{\kappa} \ln \frac{y u_*}{v_w} + \hat{B} u_* \tag{2.37}$$

where u_c is the transformed compressible velocity

$$u_c = \frac{U_\infty}{A} \sin^{-1} \left\{ \frac{2A^2 v - B}{\sqrt{B^2 + 4A^2}} \right\} + \frac{U_\infty}{A} \sin^{-1} \left\{ \frac{B}{\sqrt{B^2 + 4A^2}} \right\}$$
 (2.38)

with $v = u/U_{\infty}$ and $\hat{B} = 5.0$, and

$$A^{2} = \frac{\gamma - 1}{2} P r_{t} \frac{T_{\infty}}{T_{w}} M_{\infty}^{2}, \quad B = -\frac{P r_{t} q_{w} U_{\infty}}{c_{p} T_{w} \tau_{w}}, \tag{2.39}$$

and q_w is the heat transfer at the wall. The computed profiles demonstrate close

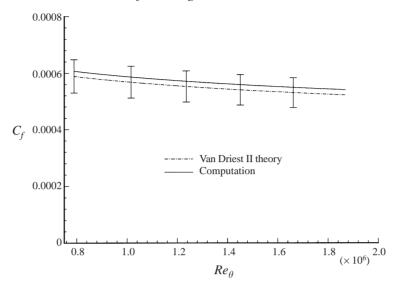


Figure 6. Skin friction for $M_{\infty} = 4$ (adiabatic).

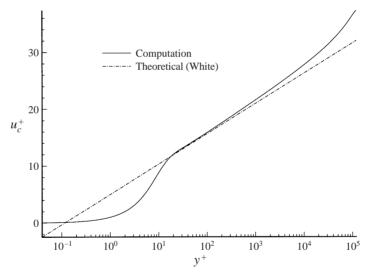


Figure 7. Velocity profile in the near-wall region for $M_{\infty} = 4$ (adiabatic).

agreement with the compressible law of the wall within a region near the wall. The computed velocity profile in the outer region is presented in figure 8 and compared with the compressible defect law (White 1974)

$$U_{e_c} - u_c = \frac{u_*}{\kappa} \left\{ 2\Pi \left[1 - \sin^2 \left(\frac{\pi}{2} \frac{y}{\delta} \right) \right] - \ln \frac{y}{\delta} \right\}$$
 (2.40)

where U_{e_c} is the transformed compressible velocity evaluated at the edge of the boundary layer δ . The defect law is a consequence of the general compressible law of the wall and wake

$$u_{c} = \frac{u_{*}}{\kappa} \ln \frac{yu_{*}}{v_{w}} + \hat{B}u_{*} + \frac{2\Pi u_{*}}{\kappa} \sin^{2}\left(\frac{\pi}{2} \frac{y}{\delta}\right)$$
 (2.41)

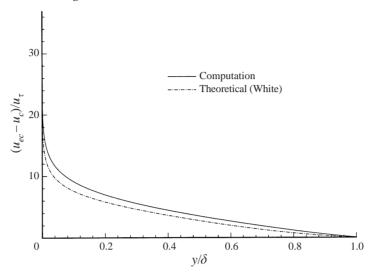


Figure 8. Velocity profile in the outer region for $M_{\infty}=4$ (adiabatic)

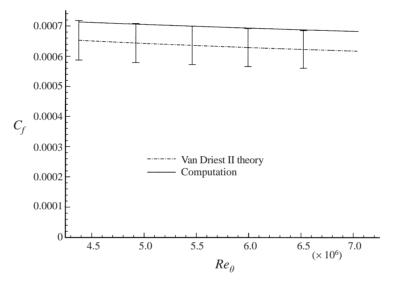


FIGURE 9. Skin friction for $M_{\infty} = 4$ (isothermal).

where $\Pi=0.55$ for a flat-plate boundary layer (White 1974). The computed profile demonstrates good agreement with the defect law.

The computed adiabatic wall temperature $T_{aw}/T_{\infty} = 3.85$, which is within 4.7% of the value obtained from asymptotic analysis of the turbulence model equations (Knight 1993a)

$$T_{adia} = T_{\infty} \left(1 + \frac{\gamma - 1}{2} \sqrt{Pr_t} M_{\infty}^2 \right). \tag{2.42}$$

Additionally, the computed adiabatic wall temperature agrees with the commonly used expression (White 1974), wherein $\sqrt{Pr_t}$ is replaced by Pr_t in (2.42), to within 2% over the same Mach number range (Becht & Knight 1995).

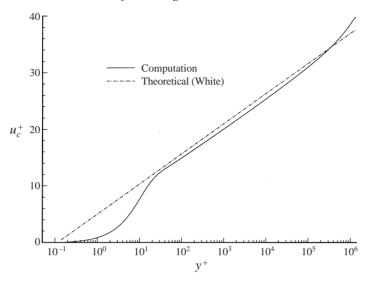


Figure 10. Velocity profile in the near-wall region for $M_{\infty} = 4$ (isothermal).

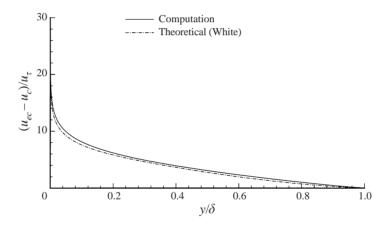


Figure 11. Velocity profile in the outer region for $M_{\infty} = 4$ (isothermal).

Mach 4 isothermal wall

The computed skin friction is compared with the empirical Van Driest II theory (Hopkins & Inouye 1971) in figure 9 for $T_w = 0.4T_{aw}$. The prediction is within the experimental uncertainty ($\pm 10\%$).

The computed Reynolds analogy factor $2C_h/C_f = 1.24$, where the heat transfer coefficient is defined as

$$C_h = \frac{q_w}{\rho_\infty U_\infty c_p (T_w - T_{adia})}. (2.43)$$

This is within 12.7% of the theoretical value of 1.1 based on asymptotic analysis of the model equations (Knight 1993a).

The computed velocity profile in the near-wall region is presented in figure 10 and compared with the compressible law of the wall (2.37). The computed profiles demonstrate good agreement. The computed velocity profile in the outer region is presented in figure 11 and compared with the compressible defect law (2.40). Excellent agreement is observed.

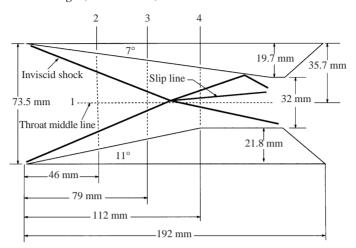


FIGURE 12. Experimental configuration for $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ (Zheltovodov *et al.*).

	Reference	M_{∞}	α_1	α_2	Re_{δ_∞}	$p_{t_{\infty}}$ MPa	$T_{t_{\infty}}$ K	δ_{∞}^{*} mm
	Case 1				3.1×10^5			
	Case 2	3.95	7°	11°	3.0×10^{5}	1.5	260	1.1
0	free-stream Mach number Reynolds number based on δ_{∞} free-stream total pressure		$T_{t_{\infty}} \ \delta_{\infty}^* \ lpha_1,lpha_2$		free-stream total temperature upstream displacement thickness fin angles (deg)			
3.	Experimental (Zheltovodov e	t al. 1	994.	1998	(a,b) and c	comput	tation	al conditions.

3. Crossing shock interaction

 M_{∞} $Re_{\delta_{\infty}}$ $p_{t_{\infty}}$

3.1. Details of computations

The computational results are compared to the experimental data of Zheltovodov et al. (1994, 1998a, b) for the $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$ and $(7^{\circ}, 11^{\circ})$ configurations. For the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ case, the computations are also compared with previous simulations by Knight et al. (1995b) using the low Reynolds number correction of Chien (1982), and by Zha & Knight (1996) using a full Reynolds stress equation (RSE) model. The experimental configuration, which consists of two fins mounted on a flat plate, is shown in figure 12 for $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$. The incoming flow parameters are summarized in table 3.

The inflow profiles were generated with a boundary layer code (Becht & Knight 1995) which utilizes the same turbulence model. The inflow profile matches the experimental displacement thickness. The thin boundary layers on sidewalls can be neglected since the reflected shock waves either intersect the sidewalls near the exit or not at all (Knight *et al.* 1995*b*; Zha & Knight 1996).

The CRAFT code (Molvik & Merkle 1989), modified to incorporate the low Reynolds number model of Becht & Knight, was used for all computations. The code solves the full three-dimensional Reynolds-averaged compressible Navier–Stokes equations coupled with the turbulence model equations. The code utilizes the method of Roe (1981) for the inviscid fluxes, central differencing for the viscous fluxes and turbulence

Reference	α_1 (deg.)	α_2 (deg.)	Wall	N_x	N_y	N_z	
Case 1a	7	7	I	101	79	49	
Case 1b	7	7	A	101	79	49	
Case 2a	7	11	I	101	81	49	
Case 2b	7	11	A	101	81	49	
Case 2c	7	11	I	202	81	49	
Case 2d	7	11	I	101	162	49	
Case 2e	7	11	I	101	81	98	
Case 2f	7	11	I	101	81	49	
Reference	$\Delta x/\delta_{\infty}$	$\Delta y_{min}/\delta_{\infty}$	$\Delta y_{max}/\delta_{\infty}$	$\Delta z_{min}/\delta_{\infty}$	$\Delta z_{max}/\delta_{\infty}$	$\Delta y_2^+ _{rms}$	$\Delta y_2^+ _{aver}$
Case 1a	0.5	2.2×10^{-4}	0.5	0.2	0.5	0.55	0.52
Case 1b	0.5	2.2×10^{-4}	0.5	0.2	0.5	0.63	0.59
Case 2a	0.5	2.2×10^{-4}	0.5	0.2	0.5	0.70	0.62
Case 2b	0.5	2.2×10^{-4}	0.5	0.2	0.5	0.80	0.72
Case 2c	0.25	2.2×10^{-4}	0.5	0.2	0.5	0.72	0.65
Case 2d	0.5	1.1×10^{-4}	0.25	0.2	0.5	0.35	0.31
Case 2e	0.5	2.2×10^{-4}	0.5	0.1	0.25	0.70	0.63
Case 2f	0.5	2.2×10^{-4}	0.5	0.2	0.5	0.68	0.60
			LEGE	ND			
N_x number of points in x					I Isothe	rmal wall	
N_y number of point							
N	r_z nu	ımber of poin	ts in z				
		n.s. grid spaci erage grid spa			ts		
	= .		4. Details of				

source terms and an approximate factorization of the Jacobian. The modified CRAFT code was validated through comparison of results for adiabatic and isothermal flatplate compressible turbulent boundary layers with separate computations performed with a boundary layer code (Becht 1994) incorporating the same turbulence model.

For each configuration, two separate computations were performed in order to determine the local heat transfer coefficient (2.43). First, the wall temperature was fixed at $T_w = 1.031 T_{t_\infty}$, and the local heat transfer $q_w(x, z)$ determined. Then, the wall was assumed adiabatic and the local adiabatic wall temperature $T_{aw}(x,z)$ was determined. This approach has been employed previously for comparison with experimental heat transfer (Knight et al. 1995b; Zha & Knight 1996; Lee, Settles & Horstman 1992).

Details of the computational grids are presented in table 4. For each case, the isothermal and adiabatic computations are indicated (e.g. Case 1a and 1b). For the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ configuration, four additional computations were performed. Three of these computations (Cases 2c to 2e) represent a grid refinement study wherein the number of grid points in each direction was successively doubled. The fourth additional computation (Case 2f) incorporated a different wall temperature $(T_w = 1.0385T_{t_x})$. The results of the four additional computations showed no significant change in the predictions of the bottom surface flow pattern, pressure, adiabatic wall temperature and heat transfer predictions within the region of comparison with experiment (Gnedin 1996). Therefore, the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ computation represents an effectively grid-converged solution. Since the grid employed for the

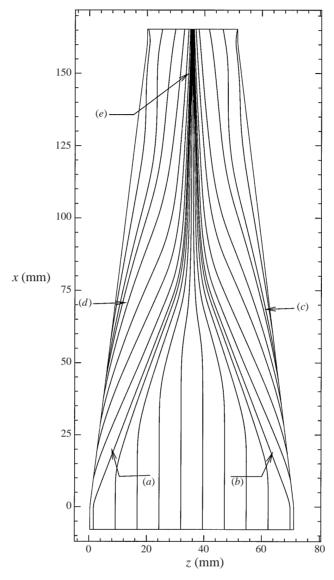


FIGURE 13. Computed skin friction lines for $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$: (a) left incident separation line; (b) right incident separation line; (c, d) lines of divergence; (e) downstream coalescence line.

weaker $(\alpha_1, \alpha_2) = (7^\circ, 7^\circ)$ case was essentially the same as used for $(\alpha_1, \alpha_2) = (7^\circ, 11^\circ)$, we therefore consider the $(\alpha_1, \alpha_2) = (7^\circ, 7^\circ)$ computation to be grid-converged also.

3.2. Results for
$$(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$$

The computed surface skin friction lines and experimental surface flow visualization for the $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$ configuration are presented in figures 13 and 14, respectively. The separation lines (lines of coalescence) (a) and (b) originating from the fin leading edges are apparent in the computation and experiment. The computed and experimental separation line angles agree within 7%. The computed skin friction lines do not intersect but, after changing direction, slowly converge towards each other. Two weak divergence lines (c) and (d) can be found near the fin surfaces.

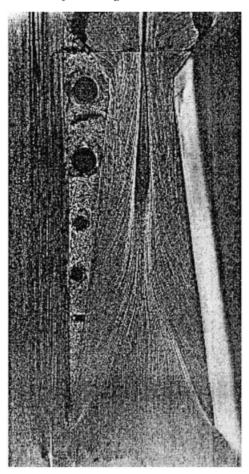


Figure 14. Experimental surface flow for $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$.

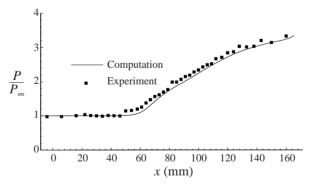


Figure 15. Wall pressure on TML for $(\alpha_1,\alpha_2)=(7^\circ,7^\circ).$

The computed and experimental surface pressure, normalized by the free-stream static pressure p_{∞} , are displayed in figures 15 and 16 along the throat middle line (TML) (the streamwise line which bisects the channel at its minimum cross section) and at the three streamwise locations. The uncertainty in the surface pressure

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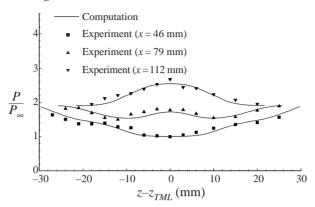


FIGURE 16. Wall pressure at x = 46 mm, x = 79 mm and x = 112 mm for $(\alpha_1, \alpha_2) = (7^\circ, 7^\circ)$.

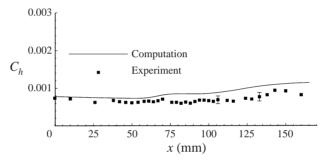


FIGURE 17. C_h on TML for $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$.

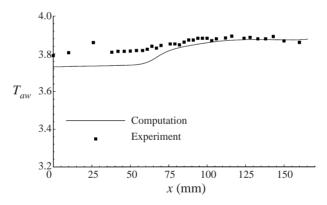


FIGURE 18. T_{aw} on TML for $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$.

measurements is $\pm 0.5\%$. The computed surface pressure displays excellent agreement with experiment.

The computed and experimental surface heat transfer coefficient C_h on the TML is presented in figure 17. The experimental uncertainty for C_h is $\pm 10\%$ to $\pm 15\%$. Reasonable agreement with the experiment is observed. The heat transfer coefficient is predicted typically within 25% in the three-dimensional interaction region. The slight increase in C_h within the three-dimensional interaction is also predicted.

The adiabatic wall temperature T_{aw} on the TML is presented in figure 18. The

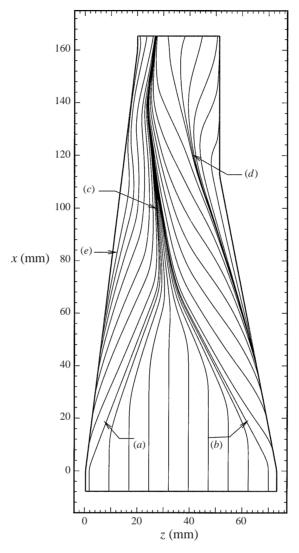


FIGURE 19. Computed skin friction lines for $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$: (a) left incident separation line; (b) right incident separation line; (c) left downstream coalescence line; (d, e) lines of divergence.

experimental uncertainty in T_{aw} is less than 0.2%. Close agreement is observed. The maximum difference between the predicted and measured T_{aw} is less than 2%.

3.3. *Results for*
$$(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$$

Figures 19 and 20 present the computed surface skin friction lines and experimental surface flow visualization respectively. It has been previously noted (Knight *et al.* 1995b; Narayanswami, Horstman & Knight 1993b) that the computed surface skin friction lines are sensitive to the turbulence model employed. Comparison of current results with figure 6 of Knight *et al.* (1995b) shows general agreement as well as a number of substantially different details. Both incident separation lines emanating from the fin leading edges (*a* and *b*) are clearly observed in figure 19 in agreement with experimental results and previous simulations of Knight *et al.* (1995b). These separation lines are associated with the incident single-fin interactions. The computed

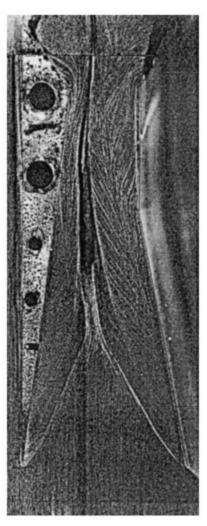


FIGURE 20. Experimental surface flow for $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$.

and experimental separation line angles, measured relative to the x-axis, agree within 9%. However, contrary to the computation with the $k-\epsilon$ Chien model (Knight et al. 1995b), the incident separation lines do not coalesce near the centre of the region, but rather continue further downstream almost in parallel until they converge at $x \approx 110 \, \text{mm}$ to form a narrow band of skin friction lines (c), which is offset to the left-hand side of the channel. This is denoted in Knight et al. (1995b) as the left downstream coalescence line, and represents the surface image of the boundary between the left-and right-hand vortices generated by the incident single-fin interactions. The vortices are evident in the crossflow velocity vectors (figure 21) at $x = 112 \, \text{mm}$. The crossflow velocity vectors near the surface change direction at (c). Lines of divergence are also apparent near the right-hand fin (d) and left-hand fin (e) associated with the incident single-fin interaction. In a major difference with the $k-\epsilon$ Chien model results, a second line of coalescence (the right downstream coalescence line) is not present in this computation. Consequently, the model does not predict a secondary separation underneath the left-hand side of the right-hand vortex (see Knight et al. 1995b). The

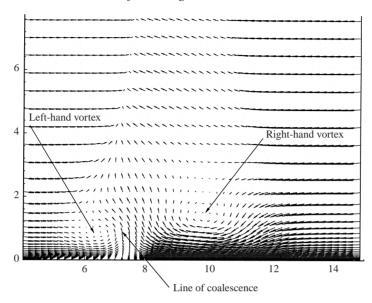


Figure 21. Crossflow velocity vectors at $x = 112 \,\mathrm{mm}$ for $(\alpha_1, \alpha_2) = (7^\circ, 11^\circ)$.

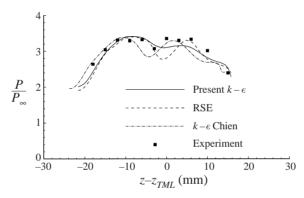


FIGURE 22. Wall pressure at $x = 112 \,\text{mm}$ for $(\alpha_1, \alpha_2) = (7^\circ, 11^\circ)$.

difference is due to deviation in the predictions of the pressure distribution in the spanwise direction, obtained with each turbulence model as described below.

The computed and experimental surface pressure distribution in the spanwise direction at $x=112\,\mathrm{mm}$, normalized by the free-stream static pressure p_∞ , is displayed in figure 22. This location corresponds to the streamwise location No. 4 (see figure 12). The plot contains computational results obtained with three different turbulence models as described above. The abscissa $z-z_{\mathrm{TML}}$ represents the spanwise distance measured from the TML. The computed and experimental surface pressure are in general agreement for all three models. However, unlike in the present computations, Chien's model predicts a local adverse pressure gradient in spanwise direction in the region $-10\,\mathrm{mm} < z-z_{\mathrm{TML}} < -4\,\mathrm{mm}$. As described in detail in Knight *et al.* (1995b), the flow near the surface at this location is moving towards the left-hand fin and the adverse pressure gradient causes the secondary separation and the appearance of the right downstream coalescence line, which is not predicted by the present computation.

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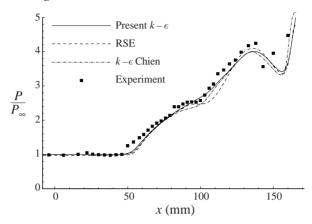


FIGURE 23. Wall pressure on TML for $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$.

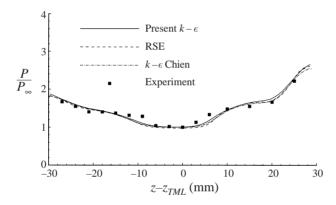


Figure 24. Wall pressure at $x=46\,\mathrm{mm}$ for $(\alpha_1,\alpha_2)=(7^\circ,11^\circ)$.

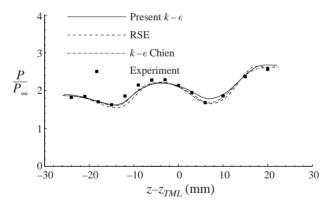


Figure 25. Wall pressure at x = 79 mm for $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$.

The computed and experimental surface pressure along the TML, displayed in figure 23, are in good agreement for $x < 135 \,\mathrm{mm}$, although the computation underestimates the extent of the upstream influence, as observed in previous studies (e.g. Narayanswami *et al.* 1992; Knight *et al.* 1995b). The computed pressure does not

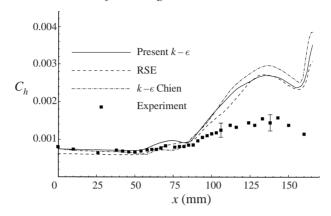


FIGURE 26. C_h on TML for $(\alpha_1, \alpha_2) = (7^\circ, 11^\circ)$.

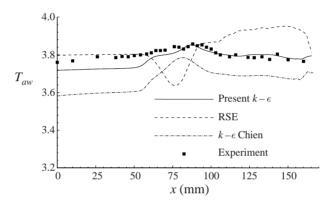


FIGURE 27. T_{aw} on TML for $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$.

accurately predict the pressure rise (beginning at $x = 145 \,\mathrm{mm}$) associated with the shock reflection from the 7° fin, since all of the computations omit the boundary layers on the fin surfaces. The computed and experimental surface pressure at x = 46 and 79 mm are displayed in figures 24 and 25. Close agreement is again observed.

The computed and experimental surface heat transfer coefficient C_h on the TML is presented in figure 26. All three turbulence models overpredict the heat transfer by approximately a factor of two downstream of the intersection of the shocks (which occurs at $x=93.7\,\mathrm{mm}$), with a modest improvement in the computations performed with RSE and present models compared to the $k-\epsilon$ Chien model. The overprediction in C_h is actually an overprediction in q_w , since a series of studies (Zha & Knight 1996; Gnedin 1996) has demonstrated that the computed q_w is proportional to the computed T_w-T_{aw} . A possible explanation is that the turbulence models overestimate the effects of the shock/boundary layer interaction on the turbulence production, thereby generating excessive turbulence kinetic energy and overestimating the turbulenct statistics within the flowfield) are needed to assist in the identification of the specific weaknesses in these models and develop improved models.

The computed and experimental T_{aw} on the TML are displayed in figures 27 and 28. The results of the present computation exhibit excellent agreement with the experiment, and represent an improvement over the predictions by the k- ϵ Chien and

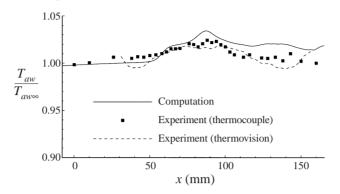


FIGURE 28. T_{aw} on TML for $(\alpha_1, \alpha_2) = (7^\circ, 11^\circ)$.

RSE (Zha & Knight) models. The experimental results for T_{aw} obtained using the thermocouple and thermovision techniques agree closely, with a maximum difference of 1.5%.

4. Conclusions

A collaborative experimental and theoretical (computational) study of a crossing-shock-wave/turbulent-boundary-layer interaction has been performed. Two configurations $-(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$ and $(7^{\circ}, 11^{\circ})$ have been examined at Mach 3.9. Experimental data include surface pressure and heat transfer, adiabatic wall temperature and surface flow visualization. The computations employ the three-dimensional Reynolds-averaged compressible Navier–Stokes equations. Turbulence is represented by the two-equation $k-\epsilon$ model with a new low-Reynolds-number model which has been validated for compressible adiabatic and isothermal flat-plate zero-pressure-gradient boundary layers. For the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ configuration, previous results obtained using the $k-\epsilon$ Chien model and a full Reynolds stress equation (Zha & Knight) model are also presented for comparison. The principal conclusions are:

The computed surface pressure displays very good agreement with experiment for the $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$ and $(7^{\circ}, 11^{\circ})$ configurations. For the $(7^{\circ}, 11^{\circ})$ case, similar very good agreement is obtained by the k- ϵ Chien and full RSE models.

The computed surface skin friction lines are in close agreement with experiment for the initial separation lines, and are in qualitative agreement within the crossing shock interaction region. However, for the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ case, the present model does not predict the secondary separation line. This feature is predicted by the $k-\epsilon$ Chien model.

The computed heat transfer is in good agreement with experimental data for the $(\alpha_1, \alpha_2) = (7^{\circ}, 7^{\circ})$ configuration. For the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ configuration, the computed heat transfer is significantly overpredicted within the three-dimensional interaction. However, a modest improvement is achieved compared to the computations with the k- ϵ Chien model, and the results are comparable with the predictions of the full RSE model

The adiabatic wall temperature is accurately predicted for all configurations. For the $(\alpha_1, \alpha_2) = (7^{\circ}, 11^{\circ})$ case, the model displays a definite improvement over the $k-\epsilon$ Chien and full RSE models.

The experimental data for T_{aw} obtained with the thermocouple and thermovision techniques are in close agreement.

Additional experimental data, including turbulence measurements within the threedimensional interaction, are needed to improve the understanding of the flow field and assist in the development of improved models.

New turbulence models are needed to improve prediction of flow-field quantities of engineering interest (e.g. surface heat transfer) which are strongly influenced by the turbulence structure.

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